

ENERGY-DEPENDENT POTENTIALS REVISITED: A UNIVERSAL HIERARCHY OF HYDRODYNAMIC TYPE *

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Abstract

A hierarchy of infinite-dimensional systems of hydrodynamic type is considered and a general scheme for classifying its reductions is provided. Wide families of integrable systems including, in particular, those associated with energy-dependent spectral problems of Schrödinger type, are characterized as reductions of this hierarchy. N -phase type reductions and their corresponding Dubrovin equations are analyzed. A symmetry transformation connecting different classes of reductions is formulated.

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1 Introduction

In this work we consider the system of evolution equations

$$\frac{\partial Y}{\partial t_i} = \langle A_i, Y \rangle, \quad A_i := (\lambda^i Y)_+, \quad i \geq 0, \quad (1)$$

where $\langle U, V \rangle := UV_x - U_x V$, and the function

$$Y = Y(\lambda, \mathbf{t}), \quad \mathbf{t} := (t_0 := x, t_1, \dots),$$

is assumed to admit an expansion

$$Y = 1 + \frac{y_1(\mathbf{t})}{\lambda} + \frac{y_2(\mathbf{t})}{\lambda^2} + \dots, \quad \lambda \rightarrow \infty.$$

Here and henceforth we will denote by $A = A(\lambda)_+ + A(\lambda)_-$ the standard decomposition of a power series of λ in its components A_+ and A_- with positive and strictly negative powers of λ , respectively. The system of equations (1) originated in the theory of the finite-gap solutions of the KdV equation (see [1]) and, in a more general context, it appears [2] in the analysis of the integrable hierarchies EDP(d) ($d \geq 1$) associated with Schrödinger spectral problems with energy-dependent potentials [3]-[9]

$$\partial_{xx}\psi = U(\lambda, x)\psi, \quad U(\lambda, x) := \lambda^d + \sum_{i=0}^{d-1} \lambda^i u_i(x). \quad (2)$$

The nonlinear evolution equations of the EDP(d) hierarchy can be written as

$$\partial_i U = -\frac{1}{2} A_{i,xxx} + 2U A_{i,x} + U_x A_i, \quad A_i = (\lambda^i Y)_+, \quad (3)$$

where the function Y can be determined by

$$Y = 2\lambda^{\frac{d}{2}} \frac{\psi_1(\lambda)\psi_2(\lambda)}{\langle \psi_1, \psi_2 \rangle}, \quad (4)$$

with ψ_1, ψ_2 being two independent solutions of (2). As a consequence of (2) and (4) it follows that

$$2Y_{xx}Y - Y_x^2 - 4UY^2 + 4\lambda^d = 0. \quad (5)$$

This equation allows us to determine the coefficients of Y as differential polynomials depending on the potential coefficients $\{u_i = u_i(x)\}_{i=0}^{d-1}$. In this way, the solutions of (1) provided by the EDP(d) hierarchy satisfy a reduction condition described by the differential constraint (5). For example

- i) In the case of the EDP(1) hierarchy , the standard KdV hierarchy, we have $U = \lambda + u_0$ and

$$\begin{aligned} u_0 &= -2y_1, \quad y_2 = \frac{3}{2}y_1^2 + \frac{1}{4}y_{1,xx}, \\ 8y_3 &= 8y_1^3 - (y_{1,x})^2 + 2y_1y_{1,xx} + 8y_1y_2 + 2y_{2,xx}. \end{aligned} \quad (6)$$

- ii) The hierarchy EDP(2) is equivalent to the Zakharov-Shabat hierarchy [3] and one finds

$$u_1 = -2y_1, \quad u_0 = 3y_1^2 - 2y_2, \quad y_3 = 12y_1y_2 - 8y_1^3 + y_{1,xx}. \quad (7)$$

- iii) For the case EDP(3) the first few relations arising from (5) are

$$u_2 = -2y_1, \quad u_1 = 3y_1^2 - 2y_2, \quad u_0 = -4y_1^3 + 6y_1y_2 - 2y_3. \quad (8)$$

The purpose of this paper is to study (1) as a hierarchy of nonlinear integrable models. In this sense, the form of (1) resembles that of the dispersionless KP hierarchy [10]-[16]

$$\frac{\partial Z}{\partial t_i} = \{B_i, Z\}, \quad B_i := (Z^i)_+, \quad i \geq 0,$$

where $\{U, V\} := U_\lambda V_x - U_x V_\lambda$ is the standard Poisson bracket operation and $Z = Z(\lambda, \mathbf{t})$ is assumed to admit an expansion

$$Z = \lambda + \frac{z_1(\mathbf{t})}{\lambda} + \frac{z_2(\mathbf{t})}{\lambda^2} + \dots, \quad \lambda \rightarrow \infty.$$

The subsequent analysis proves that the hierarchy (1), like the dispersionless KP hierarchy, has deep connections with the theory of hydrodynamic systems. In fact, we notice that, in terms of the coefficients of the expansion of Y , the hierarchy (1) becomes a set of infinite-dimensional systems of hydrodynamic type

$$\partial_i y_n = \sum_{k=1}^n \langle y_{n-k}, y_{i+k} \rangle, \quad n \geq 1. \quad (9)$$

We will show that the hierarchy (1) exhibits a rich reduction theory which includes not only the standard types of reductions of the dispersionless KP hierarchy but also reductions of *differential type* which contain, in particular, the integrable hierarchies EDP(d). From this point of view the hierarchy (1) manifests a universal character.

It should be observed that the zeros $\lambda = \gamma$ of Y are Riemann invariants for (1) as they satisfy

$$\frac{\partial \gamma}{\partial t_i} = A_i(\gamma) \partial_x \gamma. \quad (10)$$

This fact allows one to write the dynamical equations of wide families of reductions in Riemann invariant form. In the case of differential reductions, the systems (10) have to be enlarged with appropriate equations of Dubrovin type [1].

One of the results of our work is the introduction of a symmetry transformation for (1) which connects different classes of reductions. In particular, it transforms every EDP(d) hierarchy into its corresponding EDP($d + 2$) hierarchy.

2 Reductions, N -phase solutions and Dubrovin's equations

2.1 General scheme

Many interesting reductions of the hierarchy (1) can be formulated. We will be here concerned with those determined by constraints of the form

$$F(\lambda, Y_0, Y_1, \dots, Y_n)_- = 0, \quad Y_j := \partial_x^j Y, \quad (11)$$

where it is assumed that

$$\frac{\partial F}{\partial Y_n} \neq 0.$$

Reductions of this type will be henceforth referred to as *differential reductions of order n* . The condition for (11) to determine one of such reductions is that for all $i \geq 1$ the function F must satisfy

$$\frac{d F_-}{d t_i} = \left(\sum_{j=0}^n F_j \partial_i Y_j \right)_- = 0, \quad F_j := \frac{\partial F}{\partial Y_j}, \quad (12)$$

provided Y verifies (1) and (11). By taking into account that (11) implies

$$\left(\sum_{j=0}^n F_j Y_{j+1} \right)_- = 0,$$

it follows that (12) is equivalent to

$$\left(\sum_{j=0}^n F_j Y \partial_x^{j+1} A_i - \sum_{j=1}^n \left(\sum_{k=j}^n c_{kj} F_k Y_{k+1-j} \right) \partial_x^j A_i \right)_- = 0, \quad (13)$$

where

$$c_{kj} = \binom{k}{j} - \binom{k}{j-1}.$$

Thus, it is obvious that a sufficient condition for (13) to hold is that F satisfies a system of partial differential equations of the form

$$\begin{aligned} F_{j-1} - \sum_{k=j}^n c_{kj} F_k Y_{k+1-j} &= \alpha_j F + \beta_j, \quad j = 1, \dots, n \\ F_n Y &= \alpha_{n+1} F + \beta_{n+1}, \end{aligned} \quad (14)$$

for a given set $\{\alpha_j, \beta_j\}_{j=1}^{n+1}$ of entire functions of λ (i.e. $(\alpha_j)_- = (\beta_j)_- = 0$).

2.2 Differential reductions of order 0

According to the general scheme, reductions of the form

$$F(\lambda, Y)_- = 0, \quad (15)$$

can be generated by solving

$$Y \frac{\partial F}{\partial Y} = \alpha F + \beta, \quad (16)$$

for given functions $\alpha(\lambda)$ and $\beta(\lambda)$ satisfying $\alpha_- = \beta_- = 0$. The general solution of (16) is

$$\begin{aligned} \alpha &\equiv 0, \quad F = \beta(\lambda) \ln Y + a(\lambda), \\ \alpha &\neq 0, \quad F = a(\lambda) Y^{\alpha(\lambda)} - \frac{\beta(\lambda)}{\alpha(\lambda)}, \end{aligned} \quad (17)$$

where $a(\lambda)$ is an arbitrary function of λ .

One of the simplest types of reductions (15) included in the class (17) is

$$(\lambda^N Y)_- = 0, \quad N \geq 1, \quad (18)$$

which means that Y is of the form

$$Y = 1 + \frac{y_1(\mathbf{t})}{\lambda} + \cdots + \frac{y_N(\mathbf{t})}{\lambda^N}. \quad (19)$$

We will refer to the reduction (19) as the *N-phase reduction* of (1). Under the substitution (19) the hierarchy (1) becomes a finite system of hydrodynamic type for the coefficients $\{y_i\}_{i=1}^N$.

Example

For 2-phase reductions

$$Y = 1 + \frac{y_1}{\lambda} + \frac{y_2}{\lambda^2}, \quad (20)$$

the system (1) becomes

$$\begin{aligned} \partial_1 y_1 &= \partial_x y_2, & \partial_1 y_2 &= \langle y_1, y_2 \rangle, \\ \partial_n y_1 &= \partial_n y_2 = 0, & n &\geq 2. \end{aligned} \quad (21)$$

Thus, by introducing a function Z such that

$$y_1 = Z_x, \quad y_2 = Z_t, \quad t := t_1,$$

the 2-phase reductions of (1) are determined by the solutions of the homogeneous Monge-Ampere equation

$$Z_{tt} = Z_x Z_{tx} - Z_t Z_{xx}, \quad (22)$$

which in turn reduces to the linear equation

$$W_{pp} + pW_{pq} + qW_{qq} = 0,$$

under the Legendre transformation $(x, t) \mapsto (p, q)$

$$W = xp + tq - Z, \quad p = Z_x, \quad q = Z_t.$$

It should be noticed that an inhomogeneous version of the Monge-Ampere equation (22) describes the class of reductions of the dispersionless KP hierarchy which depend on two independent functions [14]-[16].

The N -phase reductions admit a complete set of Riemann invariants supplied by the zeros $\{\gamma_i\}_{i=1}^N$ of the function Y

$$Y = \frac{1}{\lambda^N} \prod_{i=1}^N (\lambda - \gamma_i).$$

Thus, under the change of dependent variables

$$\mathbf{y} = (y_1, \dots, y_N) \mapsto \boldsymbol{\gamma} = (\gamma_1, \dots, \gamma_N),$$

the system (1) can be written as

$$\partial_i \boldsymbol{\gamma} = \beta_i(\boldsymbol{\gamma}) \partial_x \boldsymbol{\gamma}, \quad i \geq 0. \quad (23)$$

Here β_i are the diagonal matrices

$$(\beta_i)_{jk} = A_i(\gamma_j) \delta_{jk} = \left(\gamma_j^i + \gamma_j^{i-1} y_1(\boldsymbol{\gamma}) + \dots + y_i(\boldsymbol{\gamma}) \right) \delta_{jk},$$

the functions $y_n(\boldsymbol{\gamma})$ are given by the symmetric polynomials

$$y_n(\boldsymbol{\gamma}) = (-1)^n \sum_I \gamma_{i_1} \cdots \gamma_{i_n},$$

and the sum extends to all subsets $I \subset \{1, \dots, N\}$ with n elements. Equations (23) are well known in the theory of N -phase solutions of the KdV hierarchy [17].

2.3 Differential reductions of order 1

Reductions of the form

$$F(\lambda, Y, Y_x)_- = 0, \quad (24)$$

can be determined by solving

$$Y \frac{\partial F}{\partial Y} = \alpha_1 F + \beta_1, \quad Y \frac{\partial F}{\partial Y_x} = \alpha_2 F + \beta_2, \quad (25)$$

for given functions α_i, β_i with $(\alpha_i)_- = (\beta_i)_- = 0$. The compatibility conditions for these equations imply

$$\alpha_1 = -1, \quad \alpha_2 = 0,$$

so that the general solution of the system (25) is

$$F = \alpha(\lambda) \frac{Y_x}{Y} + \frac{a(\lambda)}{Y} + \gamma(\lambda), \quad (26)$$

where a is an arbitrary function of λ , and we are denoting $\alpha(\lambda) := \beta_2(\lambda)$, $\gamma(\lambda) := \beta_1(\lambda)$. For a function F of the form (26) the reduction constraint (24) reads

$$\alpha(\lambda)Y_x + a(\lambda) = \beta(\lambda, \mathbf{t})Y, \quad (27)$$

where

$$\beta(\lambda, \mathbf{t}) := \left(\alpha(\lambda) \frac{Y_x}{Y} + \frac{a(\lambda)}{Y} \right)_+.$$

Examples

1) The reduction corresponding to (26) with

$$F = \alpha \frac{Y_x}{Y} + \frac{\lambda}{Y}, \quad (28)$$

where α is a given nonzero complex number, is determined by

$$\alpha Y_x + \lambda = (\lambda - y_1)Y, \quad (29)$$

or, equivalently, by the following recurrence relation for the coefficients of the expansion of Y

$$y_{i+1} = y_1 y_i + \alpha \partial_x y_i, \quad i \geq 0. \quad (30)$$

2) If we set

$$F = \alpha \frac{Y_x}{Y} + \frac{\lambda^2}{Y}, \quad (31)$$

where α is a given nonzero complex number, then the reduction constraint (27) can be written as

$$\alpha Y_x + \lambda^2 = (\lambda^2 - \lambda y_1 + y_1^2 - y_2)Y, \quad (32)$$

which imposes the following recurrence relation

$$y_{i+2} = y_1 y_{i+1} + (y_2 - y_1^2) y_i + \alpha \partial_x y_i, \quad i \geq 0. \quad (33)$$

Under appropriate conditions it is possible to formulate combinations of both N -phase and differential reductions. The coefficients $\{y_n\}_{n=1}^N$ of the corresponding function Y are constrained by a certain system of differential equations with respect to the x variable. In terms of the zeros $\{\gamma_i\}_{i=1}^N$ of Y these differential equations are of Dubrovin type [1].

For example, from (27) it follows that the condition for differential reductions of order 1 to admit a further N -phase reduction is that the function

$$\Phi := \lambda^N Y = \prod_{i=1}^N (\lambda - \gamma_i), \quad (34)$$

satisfies

$$\alpha(\lambda) \Phi_x + \lambda^N a(\lambda) = \beta(\lambda, \mathbf{t}) \Phi. \quad (35)$$

This condition can be fulfilled only if $(\lambda^N a)_- = 0$. Furthermore, by inserting (34) into (35) we get the following system of Dubrovin's equations

$$\partial_x \gamma_i = \frac{\gamma_i^N a(\gamma_i)}{\alpha(\gamma_i) \prod_{j \neq i} (\gamma_i - \gamma_j)}, \quad i = 1, \dots, N. \quad (36)$$

Examples

1) From (30) we have that the 2-phase reduction of the differential reduction (29) is determined by

$$y_2 = y_1^2 + \alpha \partial_x y_1, \quad y_n = 0, \quad n \geq 3, \quad (37)$$

where y_1 verifies the differential equation

$$\alpha^2 \partial_{xx} y_1 + 3\alpha y_1 \partial_x y_1 + y_1^3 = 0. \quad (38)$$

Let $\{\gamma_i\}_{i=1}^2$ be the zeros of Y , then we can write $y_1 = \gamma_1 + \gamma_2$, $y_2 = \gamma_1 \gamma_2$. Moreover, (37) and (38) lead to the Dubrovin's equations

$$\alpha \partial_x \gamma_i = \frac{\gamma_i^3}{\prod_{j \neq i} (\gamma_i - \gamma_j)}, \quad i = 1, 2. \quad (39)$$

We observe that this reduction describes the 2-phase solutions of Burgers equation. Indeed, according to (21) and (37) it follows

$$u_t = \alpha u_{xx} + 2uu_x, \quad u := y_1, \quad t := t_1. \quad (40)$$

2) Equation (33) implies that the 2-phase reduction satisfying the condition (32) is characterized by

$$y_2 = \frac{1}{2}(y_1^2 - \alpha \frac{\partial_x y_1}{y_1}), \quad y_n = 0, \quad n \geq 3, \quad (41)$$

where y_1 verifies

$$-2\alpha^2 y_1 \partial_{xx} y_1 + 4\alpha y_1^3 \partial_x y_1 + 3\alpha^2 (\partial_x y_1)^2 - y_1^3 = 0. \quad (42)$$

These equations lead to the Dubrovin's equations

$$\alpha \partial_x \gamma_i = \frac{\gamma_i^4}{\prod_{j \neq i} (\gamma_i - \gamma_j)}, \quad i = 1, 2. \quad (43)$$

From (21) and (41) we have that this reduction represents the 2-phase solutions of the evolution equation

$$u_t = -\frac{1}{2} \partial_x \left(\alpha \frac{u_x}{u} - u^2 \right), \quad u := y_1, \quad t := t_1. \quad (44)$$

2.4 Differential reductions of order 2

Let us consider now differential reductions of second order

$$F(\lambda, Y, Y_x, Y_{xx})_- = 0.$$

They are characterized by the solutions of

$$\begin{aligned} Y \frac{\partial F}{\partial Y} - Y_{xx} \frac{\partial F}{\partial Y_{xx}} &= \alpha_1 F + \beta_1, \\ Y \frac{\partial F}{\partial Y_x} + Y_x \frac{\partial F}{\partial Y_{xx}} &= \alpha_2 F + \beta_2, \\ Y \frac{\partial F}{\partial Y_{xx}} &= \alpha_3 F + \beta_3, \end{aligned} \quad (45)$$

for given functions $\alpha_i(\lambda)$, $\beta_i(\lambda)$ with $(\alpha_i)_- = (\beta_i)_- = 0$. Equivalently, these conditions can be expressed as

$$\begin{aligned}\frac{\partial F}{\partial Y} &= \frac{\alpha_1 F + \beta_1}{Y} + \frac{Y_{xx}}{Y^2}(\alpha_3 F + \beta_3), \\ \frac{\partial F}{\partial Y_x} &= \frac{\alpha_2 F + \beta_2}{Y} - \frac{Y_x}{Y}(\alpha_3 F + \beta_3), \\ \frac{\partial F}{\partial Y_{xx}} &= \frac{\alpha_3 F + \beta_3}{Y}.\end{aligned}\tag{46}$$

The compatibility conditions for these equations imply

$$\alpha_1 = -2, \quad \alpha_2 = \alpha_3 = \beta_2 = 0,$$

and the following general solution of (46) arises

$$F = \alpha(\lambda) \left(\frac{Y_{xx}}{Y} - \frac{1}{2} \frac{Y_x^2}{Y^2} \right) + \frac{a(\lambda)}{Y^2} + \beta(\lambda),\tag{47}$$

where $a = a(\lambda)$ is an arbitrary function and $\alpha(\lambda) := \beta_3(\lambda)$, $\beta(\lambda) := -\beta_3(\lambda)/2$.

If we set

$$\alpha(\lambda) = 2, \quad a(\lambda) = 4\lambda^d,\tag{48}$$

in (47), it follows that the corresponding reductions are the hierarchies EDP(d) associated to the Schrödinger spectral problems with energy-dependent potentials (2)-(3). Indeed it is enough to observe that (47) and (48) determine a reduction characterized by an equation of the form

$$2Y_{xx}Y - Y_x^2 - 4UY^2 + 4\lambda^d = 0,\tag{49}$$

where U is a polynomial in λ

$$U(\lambda, \mathbf{t}) := \lambda^d + \sum_{i=0}^{d-1} \lambda^i u_i(\mathbf{t}),\tag{50}$$

the coefficients of which can be recursively found from those of Y through (49).

From (49) it is clear that the EDP(d) hierarchies admit N -phase reductions. If we introduce

$$\Phi := \lambda^N Y = \prod_{i=1}^N (\lambda - \gamma_i),\tag{51}$$

then (49) reads

$$2\Phi_{xx}\Phi - \Phi_x^2 - 4U\Phi^2 + 4\lambda^{d+2N} = 0, \quad (52)$$

which is equivalent to the following system of Dubrovin's equations

$$(\partial_x\gamma_i)^2 = \frac{4\gamma_i^{d+2N}}{\prod_{j\neq i}(\gamma_i - \gamma_j)^2}, \quad i = 1, \dots, N. \quad (53)$$

3 Symmetry transformations

The hierarchy (1) exhibits an interesting type of symmetry transformations. Let

$$Y = 1 + \frac{y_1(\mathbf{t})}{\lambda} + \frac{y_2(\mathbf{t})}{\lambda^2} + \dots$$

be a solution of (1), and take a solution $X = X(t_1, t_2, \dots)$ of the associated system of differential equations

$$\partial_i X + y_i(X, t_1, t_2, \dots) = 0, \quad i \geq 1, \quad (54)$$

then it follows that the function

$$Y'(\lambda, \mathbf{t}') := Y(\lambda, \mathbf{t}(\mathbf{t}')), \quad (55)$$

where $\mathbf{t}' := (x', t'_1, t'_2, \dots, t'_n, \dots)$ and

$$\mathbf{t}(\mathbf{t}') := (X(x', t'_1, \dots), x', t'_1, \dots, t'_{n-1}, \dots), \quad (56)$$

is also a solution of (1). In order to prove this property we notice that from (1) it follows at once that

$$\partial_i A_j - \partial_j A_i = \langle A_i, A_j \rangle, \quad A_i := (\lambda^i Y)_+, \quad (57)$$

which means that (1) defines a family of commuting vector fields in the space of Laurent series of λ with coefficients depending on $\{y_i\}_{i \geq 1}$. By setting $\lambda = 0$ in (57) we find

$$\partial_i y_j - \partial_j y_i = \langle y_i, y_j \rangle. \quad (58)$$

Hence, the *contracted* vector fields

$$\mathcal{D}_i := \partial_i - y_i \partial_x, \quad i \geq 1, \quad (59)$$

form a commutative family as well. In this way, given a solution $Y = Y(\lambda, \mathbf{t})$ of (1) then one has

$$\mathcal{D}_i Y = \langle (\lambda^{i-1} Y)_+, Y \rangle_1, \quad i \geq 1,$$

where $\langle A, B \rangle_1 := A\partial_1 B - B\partial_1 A$. Therefore, it readily follows that Y' is also a solution of (1) and, consequently, the transformation $Y \rightarrow Y'$ is a symmetry of the hierarchy (1).

Example

An elementary solution of (22) is given by

$$Z = -\frac{a}{b}e^{-bt} + \frac{b}{2}x^2.$$

It determines the following 2-phase solution of (1)

$$Y = 1 + \frac{bx}{\lambda} + \frac{ae^{-bt_1}}{\lambda^2}.$$

The associated system (54) is

$$\frac{\partial X}{\partial t_1} + bX = 0, \quad \frac{\partial X}{\partial t_2} + ae^{-bt_1} = 0,$$

which has the solution

$$X = (c - at_2)e^{bt_1}.$$

Hence, from (55) we get a new solution of (1)

$$Y = 1 + \frac{b(c - at_1)e^{-bx}}{\lambda} + \frac{ae^{-bx}}{\lambda^2}.$$

An interesting aspect of the transformation $Y \rightarrow Y'$ is that it establishes some relationships between different differential reductions of (1). We notice that (54) and (55) imply

$$\begin{aligned} Y_x &= \frac{1}{\lambda}(\partial_{x'} Y' + \partial_x y_1 Y'), \\ Y_{xx} &= \frac{1}{\lambda^2} \left(Y'_{x'x'} + \partial_x y_1 Y'_{x'} + (\lambda \partial_{xx} y_1 + \partial_{xx} y_2 - y_1 \partial_{xx} y_1) Y' \right), \end{aligned} \quad (60)$$

These formulas are useful to analyze the transformation properties of the differential reductions under $Y \rightarrow Y'$. For example, if Y satisfies a differential reduction (27) of order 1

$$\alpha(\lambda)Y_x + a(\lambda) = \beta(\lambda, \mathbf{t})Y, \quad (61)$$

then Y' satisfies a similar differential reduction

$$\alpha(\lambda)Y'_{x'} + \lambda a(\lambda) = \left(\lambda\beta(\lambda, \mathbf{t}(\mathbf{t}')) - \alpha(\lambda)\partial_x y_1 \right) Y'. \quad (62)$$

The way in which EDP(d) reductions transform under (54)-(55) is particularly simple. Indeed, let us suppose that Y satisfies

$$2Y_{xx}Y - Y_x^2 - 4UY^2 + 4\lambda^d = 0, \quad U(\lambda, x) := \lambda^d + \sum_{i=0}^{d-1} \lambda^i u_i(x), \quad (63)$$

then, as a consequence of (60), the transformed function Y' verifies

$$2Y'_{x'x'}Y' - (Y'_{x'})^2 - 4U'Y'^2 + 4\lambda^{d+2} = 0, \quad (64)$$

where

$$U' := \lambda^2 U - \frac{1}{2}(\lambda\partial_{xx}y_1 + \partial_{xx}y_2 - y_1\partial_{xx}y_1) + \frac{1}{4}(\partial_x y_1)^2. \quad (65)$$

This means that $Y \rightarrow Y'$ transforms the EDP(d) hierarchy into the EDP($d+2$) hierarchy. In particular, this result proves that the whole family of hierarchies of integrable models associated with energy-dependent Schrödinger problems can be generated from its two first members, namely: the KdV hierarchy and the Zakharov-Shabat hierarchy.

From (60) one can also derive the transformation properties of Dubrovin's equations under the symmetry $Y \rightarrow Y'$. Obviously, if Y satisfies a N -phase reduction so does Y' . Moreover, the zeros of Y transform as $\gamma'_i(\mathbf{t}') = \gamma_i(\mathbf{t}(\mathbf{t}'))$ and (60) lead to identities of the type $\partial_{x'}\gamma'_i = \gamma'_i\partial_x\gamma_i$.

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